OpenSees Integration Module

Pedram Mortazavi, M.A.Sc., P.Eng. Ph.D. Student University of Toronto



2017 UT-SIM Workshop

Outline

OpenSees – OpenSees Multi-Platform Simulation

- Communication Overview
- Example Structure
- Stample Problem

OpenSees – MATLAB/C++ Multi-Platform Simulation

- Communication Overview
- Example Structure
- Stample Problem

OpenSees – VecTor2 Multi-Platform Simulation

- Communication Overview
- Structure
- Example Problem



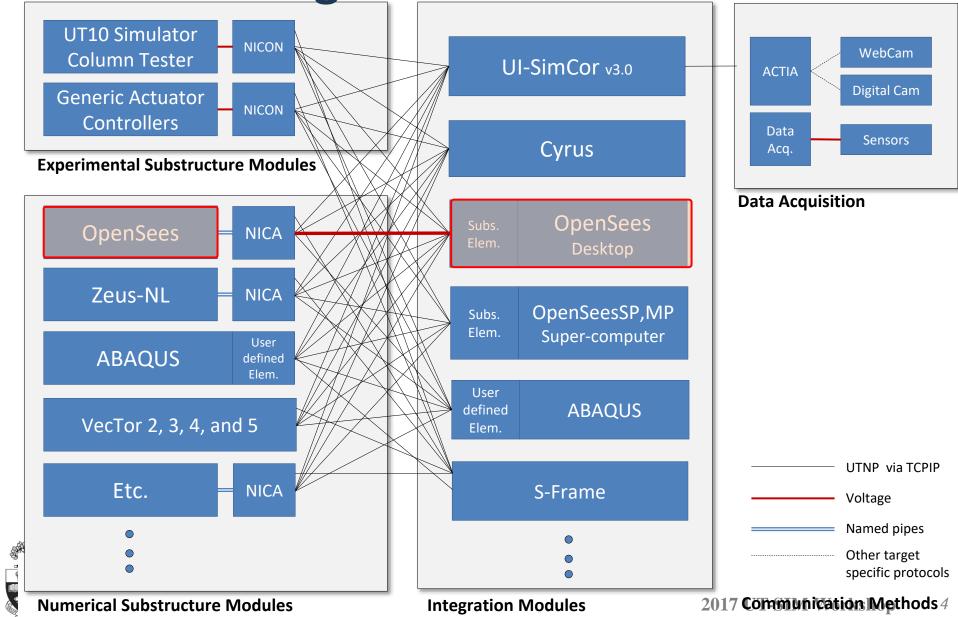


OpenSees – OpenSees Multi-Platform Simulation UT-SIM Example Manual Chapter 3



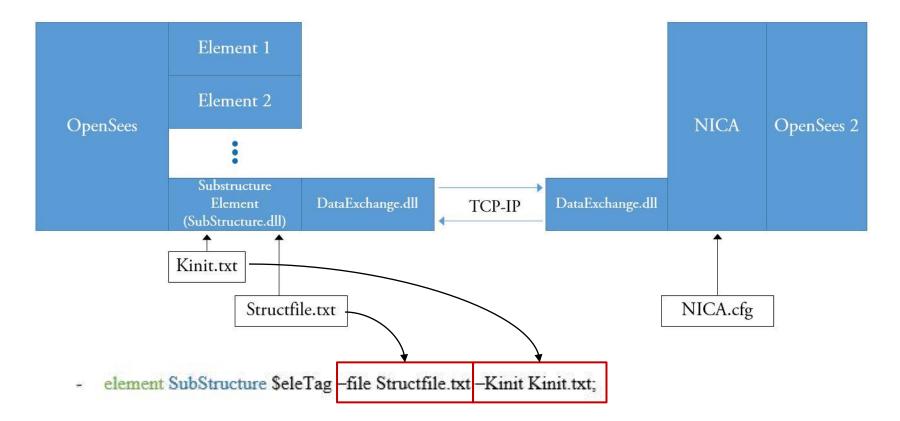
2017 UT-SIM Workshop *3*

Model Integration Method



4

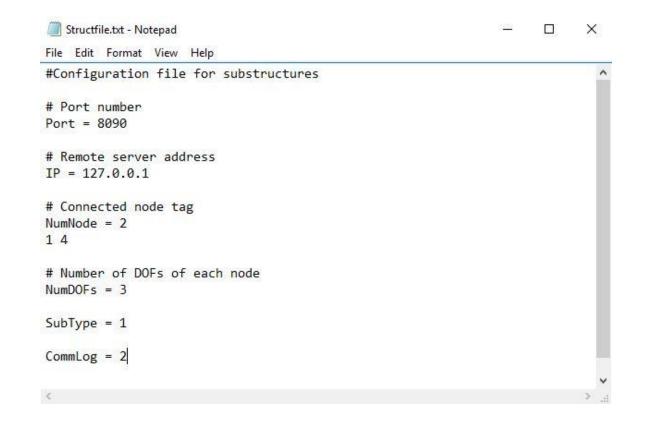
Communication Overview





□ Communication Overview

Located in the folder containing the integration module





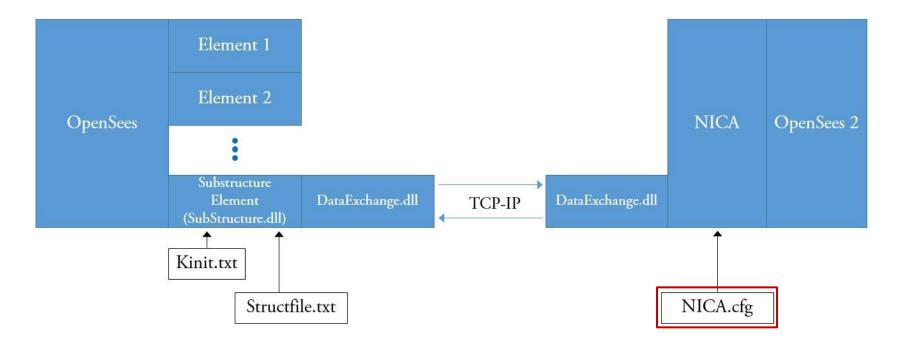
□ Communication Overview

Located in the folder containing the integration module

File	Edit	Format	View	He	lp				
22.	9621	12.62	92	0	-22.9621	-12.62	292	0	1
12.	6292	6.94	605	0	-12.6292	-6.946	505	0	
0		0		0	0	0		0	
-22	.9621	-12.6	292	0	22.9621	12.629	92	0	
-12	.6292	-6.94	605	0	12.6292	6.946	505	0	
0		0		0	0	0		0	
<								>	



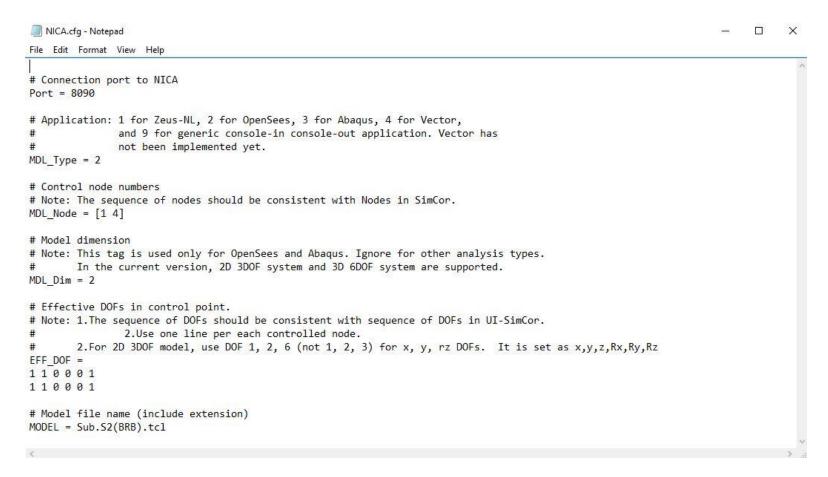
Communication Overview





□ Communication Overview

Located in the folder containing the NICA.exe file





OpenSees Script Example

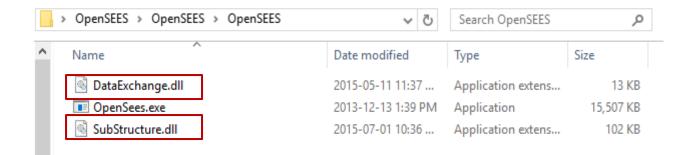
♦ Standalone model

```
puts "Define Elements";
element corotTruss 1 1 4 1 : # BRB defined as a truss element
element elasticBeamColumn 2 1 3 $Ac $E $Ic $TFrame; # Column Element Between Nodes 1 & 3
element elasticBeamColumn 3 2 4 $Ac $E $Ic $TFrame; # Column Element Between Nodes 2 & 4
element corotTruss 4 3 4 2 ; # Beam Element Defined
  Integration model
puts "Define Elements";
element SubStructure 1 -file Structfile.txt -Kinit Kinit.txt
element elasticBeamColumn 2 1 3 $Ac $E $Ic $TFrame: # Column Element Between Nodes 1 & 3
element elasticBeamColumn 3 2 4 $Ac $E $Ic $TFrame: # Column Element Between Nodes 2 & 4
element corotTruss 4 3 4 2; # Beam Element Defined
```



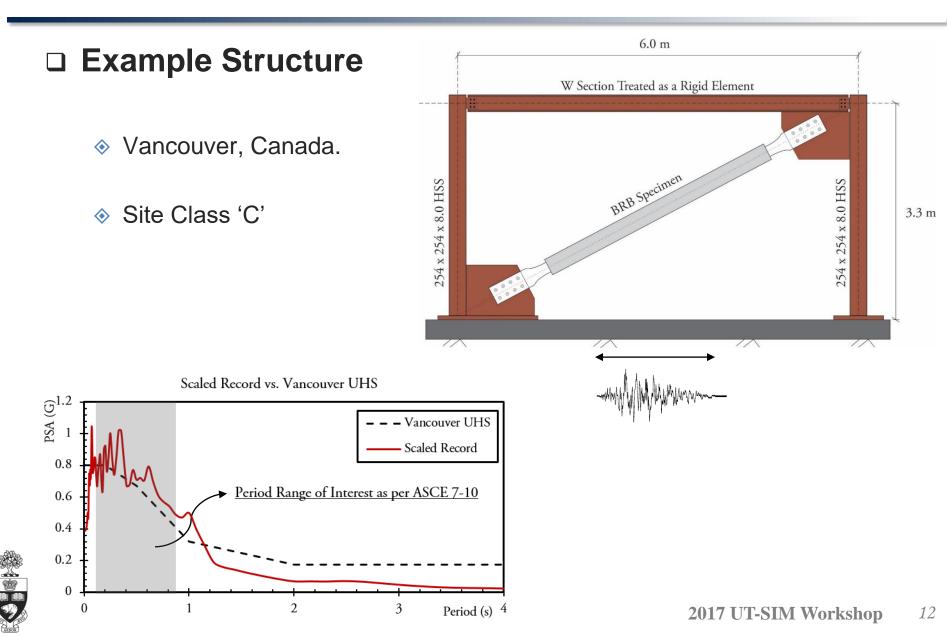
□ Required Steps for the Analysis

1. Place the DataExchange and the SubStructure .dll files in the OpenSees folder.

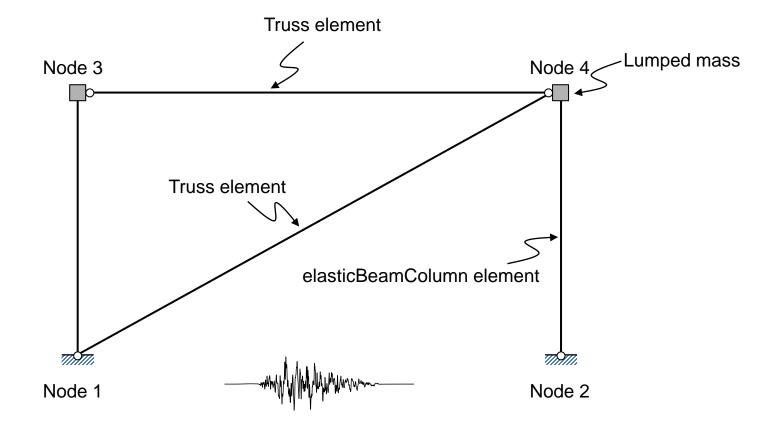


2. Place a copy of the HSF zip folder on the C drive.



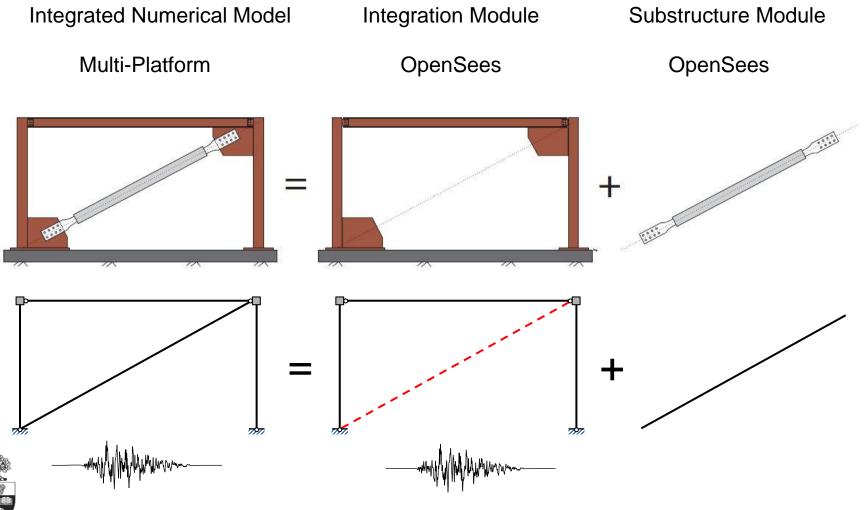


Analytical Modelling





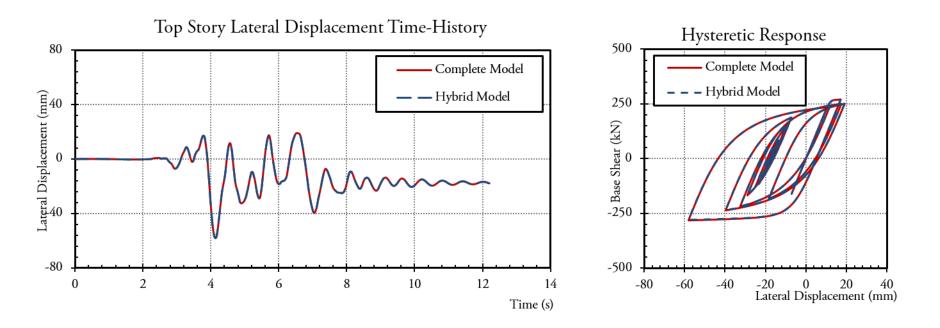
Analytical Substructures



Example Demonstration



Results





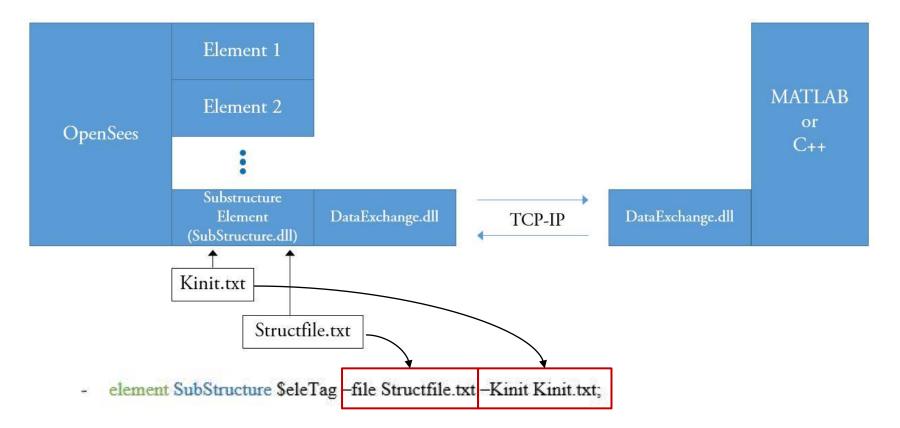


OpenSees – MATLAB/C++ Multi-Platform Simulation UT-SIM Example Manual Chapter 4 and 5

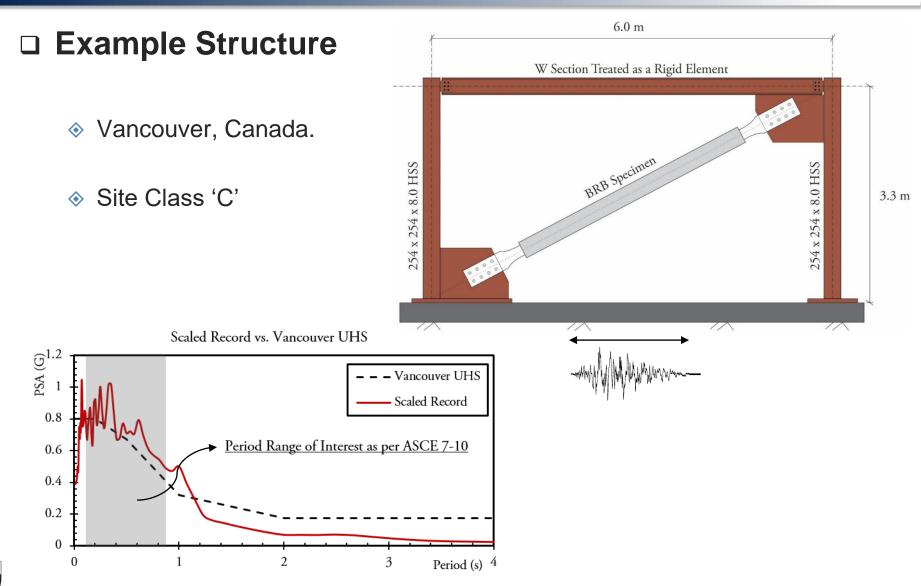


2017 UT-SIM Workshop *17*

Communication Overview







□ Required Steps for the Analysis

In addition to the previous steps required for the OpenSees – OpenSees case, place the DataExchange files in the folder containing the MATLAB substructure.

MATLAB_Substructure			~ Ō	ructure 🔎	
^	Name	^	Date modified	Туре	Size
	🚳 DataExchange.dll		2016-06-19 11:17	Application extens	20 KB
	🖻 DataExchange.h		2016-06-16 10:18	C/C++ Header	4 KB
	🕍 Server.m		2016-12-26 8:30 PM	MATLAB Code	4 KB



□ MATLAB/C++

```
    MATLAB SubStructure Script
    Clear all; close all; clc
```

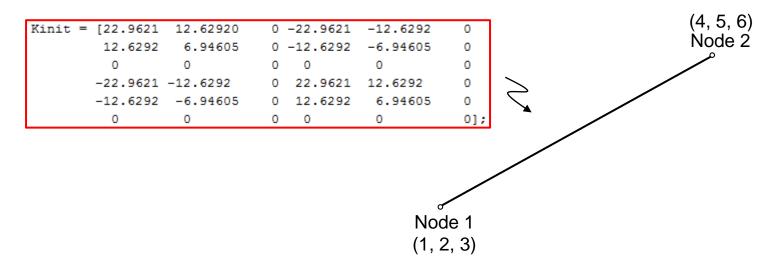
loadlibrary('./DataExchange.dll', './DataExchange.h');

```
% define socket variables
PortNumber = 8090;
```

```
machineInetAddr = libpointer('cstring','0.0.0.0');
```

sockfd = 0;
flag = 2;

% define initial stiffness matrix



□ MATLAB/C++

- ♦ Main loop (i.e. MATLAB)
 - Receive displacement

```
case Impose_TargetValues
```

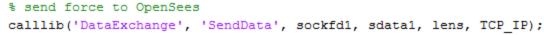
% calculate the size to be appended to the message header lens = calllib('DataExchange', 'indicator');

```
%receive displacement from OpenSees
rdata = libpointer('doublePtr', zeros(lens,1));
calllib('DataExchange', 'RecvData', sockfd1, rdata, lens, TCP_IP);
displ = get(rdata, 'value');
```

Send restoring force

```
case Report_Values
```

% calculate the size to be appended to the message header lens = calllib('DataExchange', 'indicator'); % calculate restoring force force = Kinit * displ; sdata = [displ; force]; sdata1 = libpointer('doublePtr', sdata);
Can be replaced with the algorithm for nonlinear elements

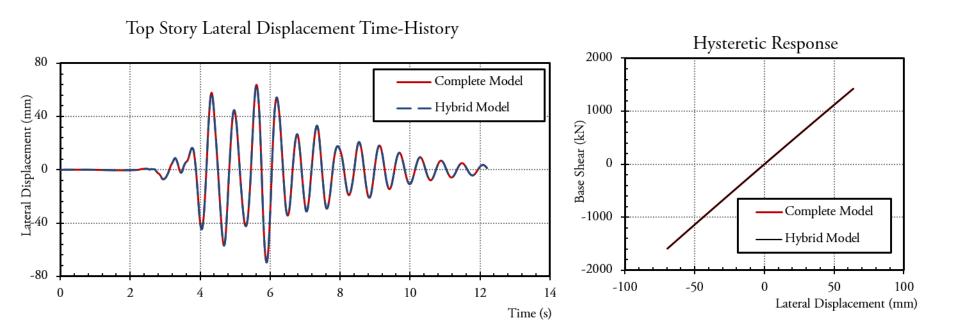




Example Demonstration



□ Results





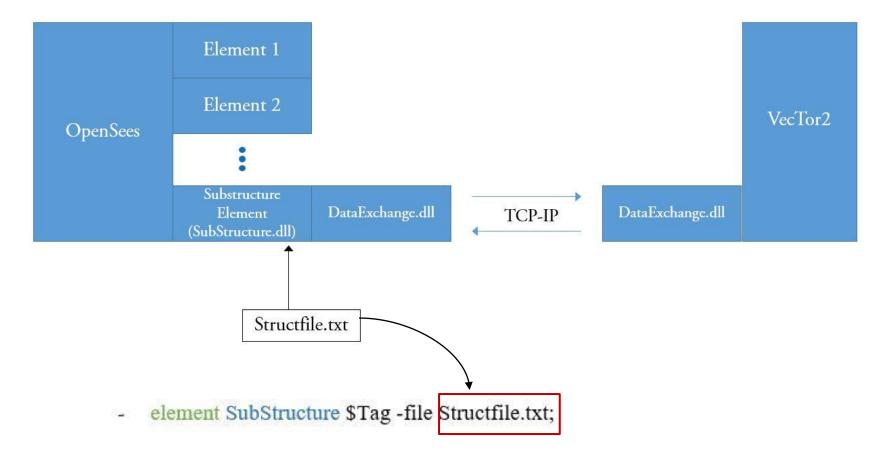


OpenSees – VecTor2 Multi-Platform Simulation UT-SIM Example Manual Chapter 10



2017 UT-SIM Workshop 25

Communication Overview



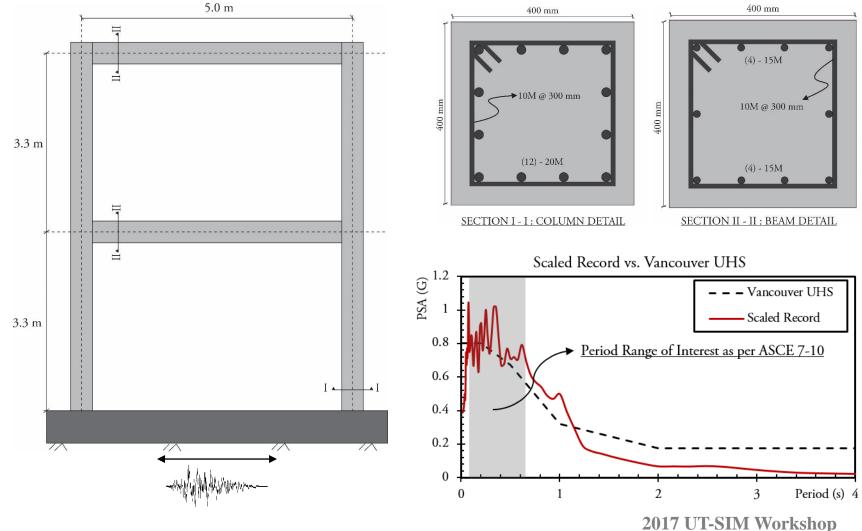


PARDISO Solver Project

- 1. Go to http://www.pardiso-project.org/.
- 2. Download the academic license.
- 3. When completing the forms, the website asks for a user name. Specify the computer username as the user name.
- 4. After completing the procedure, the user will receive an email from the PARDISO project with the download link, and the license key.
- 5. Copy the license key into a .txt file named 'pardiso.lic'. This file must be placed in the same folder where the VecTor2 substructure is located.

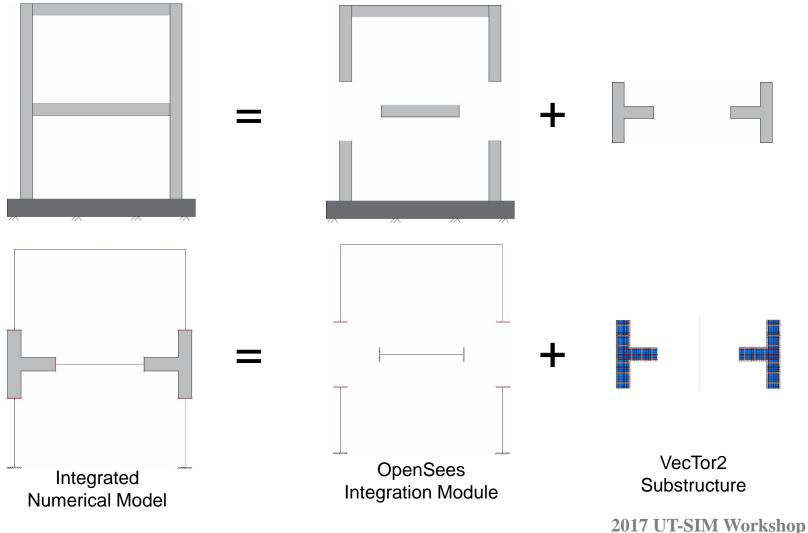


Example Structure



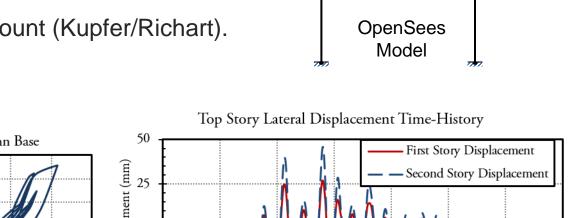
28

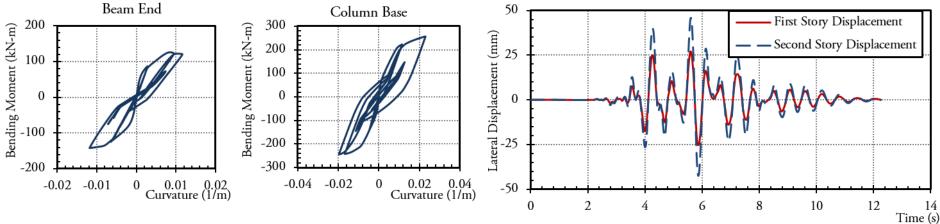
Analytical Substructures



□ Standalone OpenSees Model

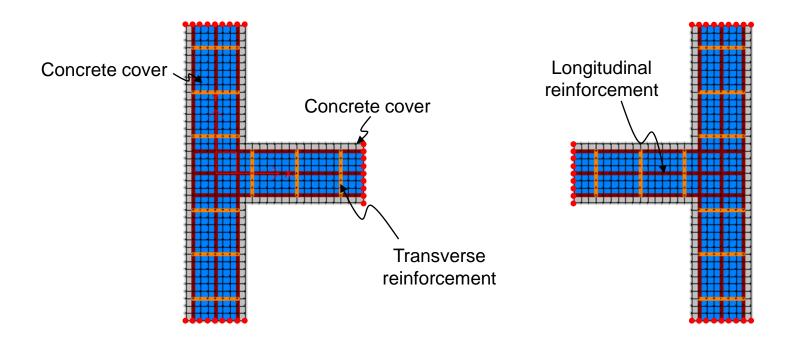
- 1. Fiber Model.
- 2. Linear shear behaviour.
- 3. Confinement taken into account (Kupfer/Richart).







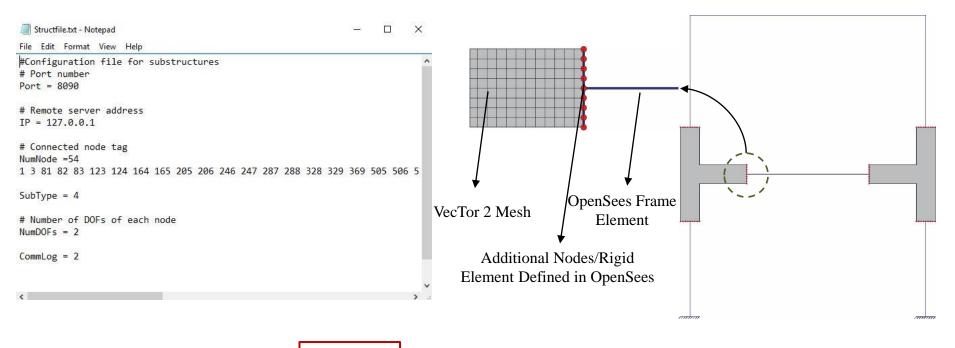
VecTor2 Substructure Module



Interface nodes



OpenSees Integration Module



element SubStructure \$Tag -file Structfile.txt;



□ Simulation Steps

- ♦ Save the 'pardiso.lic' in the SS Folder.
- ♦ Generate and Save the VecTor2 Structure File in the SS Folder.
- Senerate and Save the VecTor2 .job File in the SS Folder (can change modelling Assumptions).
- Check the Number of Analysis Steps.



□ V2 Job File

File Edit Search View Encoding Language Settings Tools Macro Run Plugins Window ?

🔚 VecTorjob 🖾			
1 VER 3.8	* * * * * * * * * * * *		
3	* VECTOR *		
4	* JOB DATA *		
5	* * * * * * * * * * *		
6			
7 Job Title (30 char. max.	: Enter Job Title		
8 Job File Name (8 char. max. 9 Date (30 char. max.	: VecTor : Enter Date		
10 (30 Char. max.	: Enter Date		
11 STRUCTURE DATA			
12			
13 Structure Type	: 2		
14 File Name (8 char. max.	: Struct		
15			
16 LOADING DATA			
17 18 No. of Load Stages	: 12000000		
19 Starting Load Stage No.	: 1		
20 Load Series ID (5 char. max.			
21			
22 Load File Name	Factors	Initial	
		Inc Load Stage	
		1000 1	
	0000 0.0000 0.0000 1 1 0.0		
	0000 0.0000 0.0000 1 1 0.0 0000 0.0000 0.0000 1 1 0.0		
	0000 0.0000 0.0000 1 1 0.0		
29 3 NODE 0	0.0000 0.0000 1 1 0.0		
30 ANALYSIS PARAMETERS			
31			
32 Analysis Mode	(1-2) : 1		
33 Seed File Name (8 char. m			
34 Convergence Limit 35 Averaging Factor	(>1.0) : 1.000010 (<1.0) : 0.600		
35 Averaging factor 36 Maximum No. of Iterations	(<1.0) : 0.600 : 60		
37 Convergence Criteria	(1-5) : 1		
38 Results Files	(1-4) : 1		
39 Modeling Format	(1-2) : 3		
40			
41 MATERIAL BEHAVIOUR MODELS			
42			
43 Concrete Compression Base Curv	(0-3) : 1 (0-3) : 1		
44 Concrete Compression Post-Peak 45 Concrete Compression Softening	(0-3) : 1 (0-8) : 1		
46 Concrete Tension Stiffening	(0-6) : 1		
	(



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NICON.txt File

NOTE: THE INTERFACE NODES MUST BE SPECIFIED WITH THE SAME SEQUENCE, IN THE INTEGRATION MODULE AND THE SUBSTRUCTURE MODULE, AND IN AN <u>ASCENDING</u> ORDER.

'287 1 1' : At node 287 force/displacement are communicated in the X and Y directions

NICON.TXT - Notepad × File Edit Format View Help Format: Number of coupled DOFs Local Node Number DOFx DOFV $DOFs = 2 \times Nodes$ 108 1 1 1 3 1 1 81 1 1 82 1 1 83 1 1 123 1 1 124 1 1 164 1 1 165 1 1 205 1 1 206 1 1 VecTor2 Node# 246 1 1 247 1 1 287 1 1



□ SS Folder

Name Case1.L2E Struct.S2E VecTor.job NICON.TXT Struct.s2r pardiso.lic VT2-14JAN16.exe Debug.txt TXT. TXT. Case1.l2r VecTor.job.bak 🗋 VT2.AUX DataExchange.dll msvcr110d.dll VECTOR.SFD libpardiso500-WIN-X86-64.dll 聞 libpardiso500-WIN-X86-64.exp III libpardiso500-WIN-X86-64.lib libiomp5md.dll



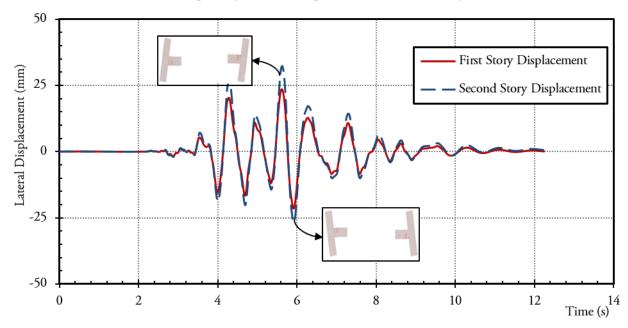
OpenSees – VecTor2

Example Demonstration and Results



□ Results can be viewed in:

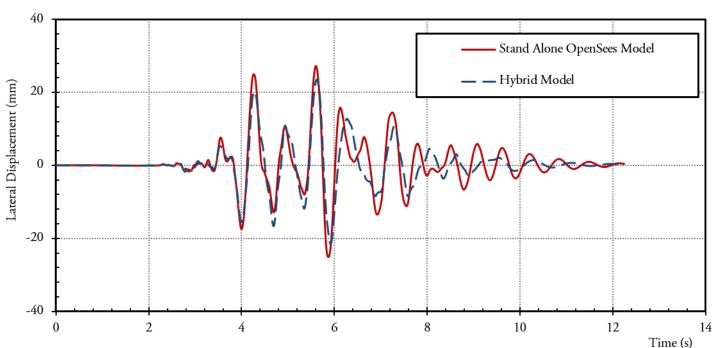
- Augustus
- Comm_log.log File
- OpenSees Displacement Recorders



Top Story Lateral Displacement Time-History



□ Comparison



First Story Displacement Time-Histories



OpenSees Integration Module

<u>Thank you</u>

pedram.mortazavi@mail.utoronto.ca



2017 UT-SIM Workshop 40